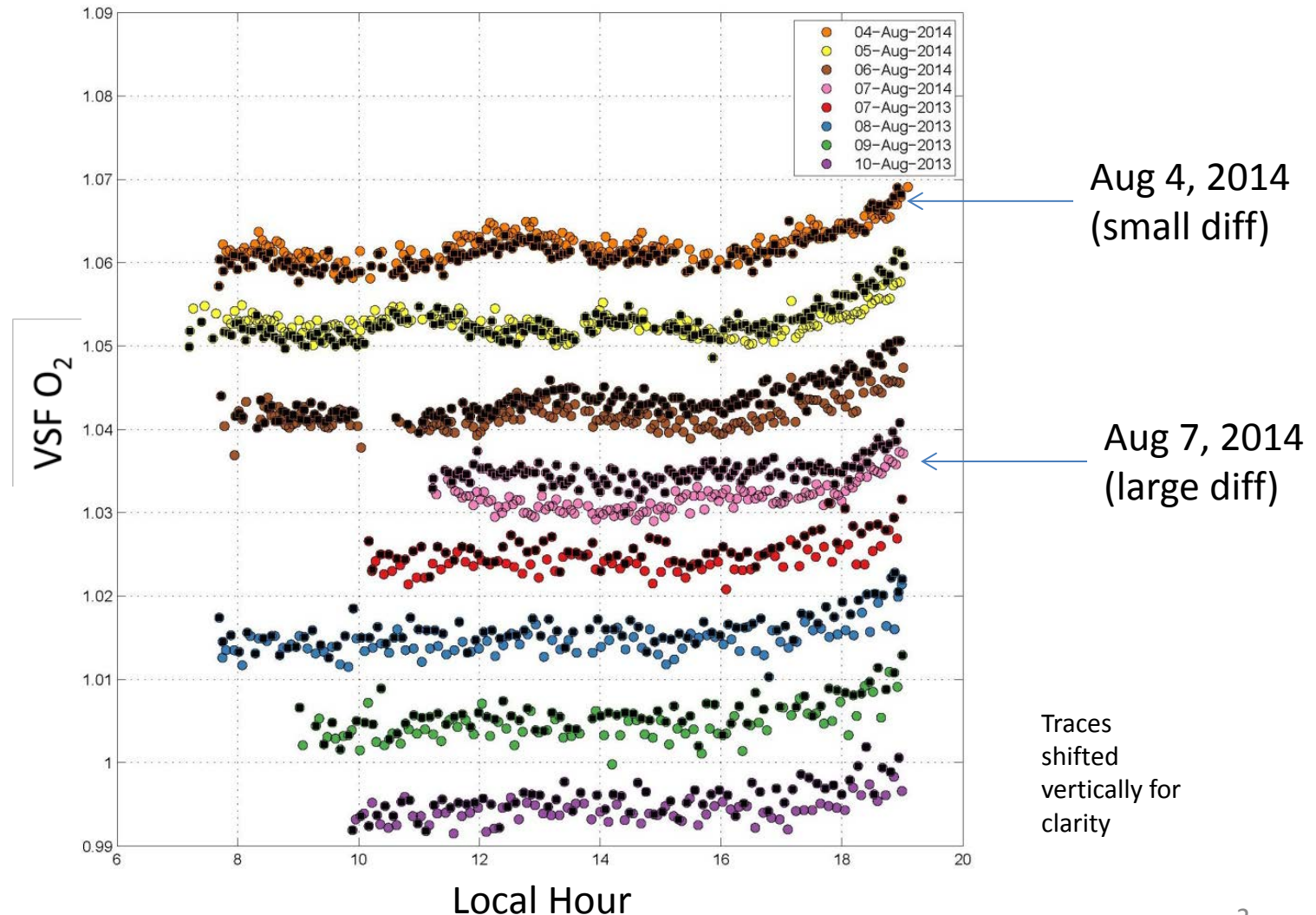


A FWD/REV Problem in Caltech Data

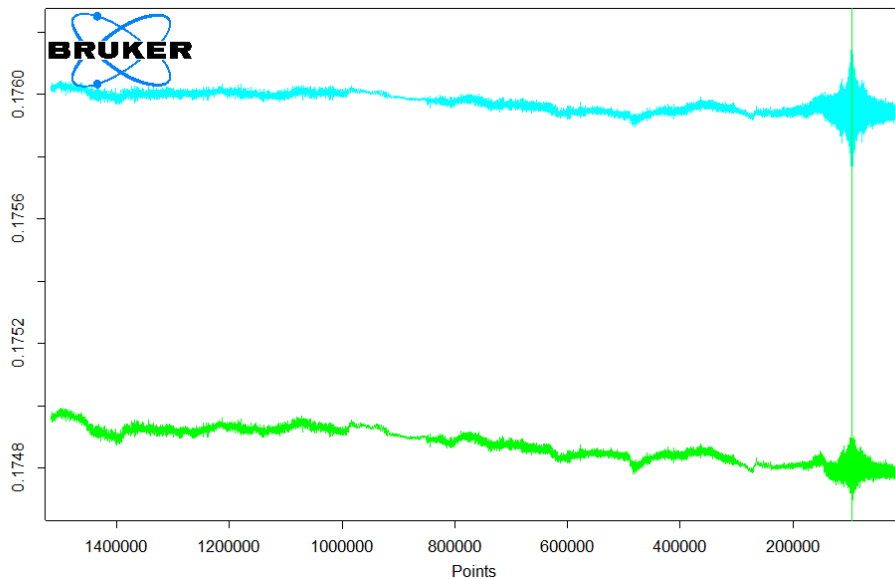
Debra Wunch, Camille Viatte, Paul Wennberg, Geoff Toon, Jean-François Blavier, Coleen Roehl, Gregor Surawicz

Forward and Reverse Scans Sometimes Differ Systematically

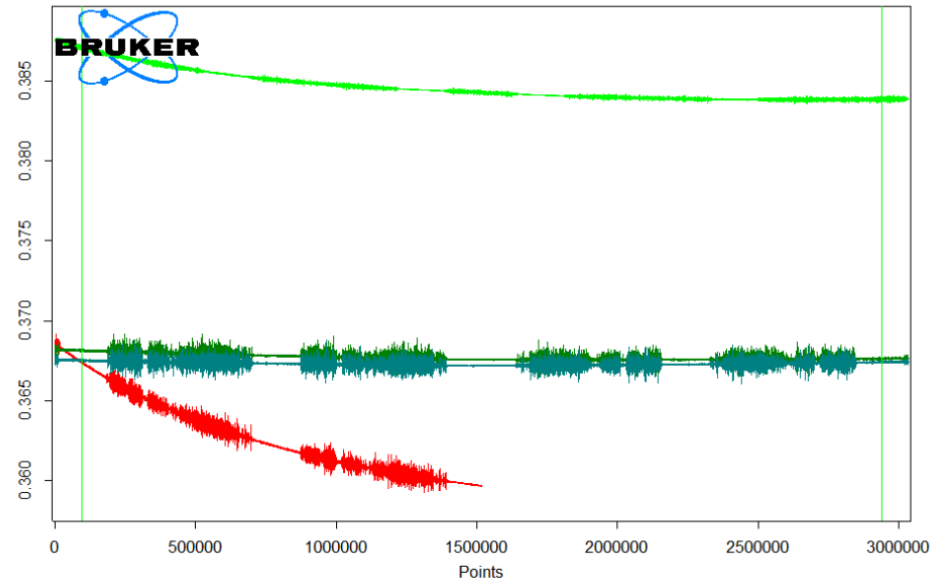


Interferograms have periodic noise “bursts”

Solar Scans

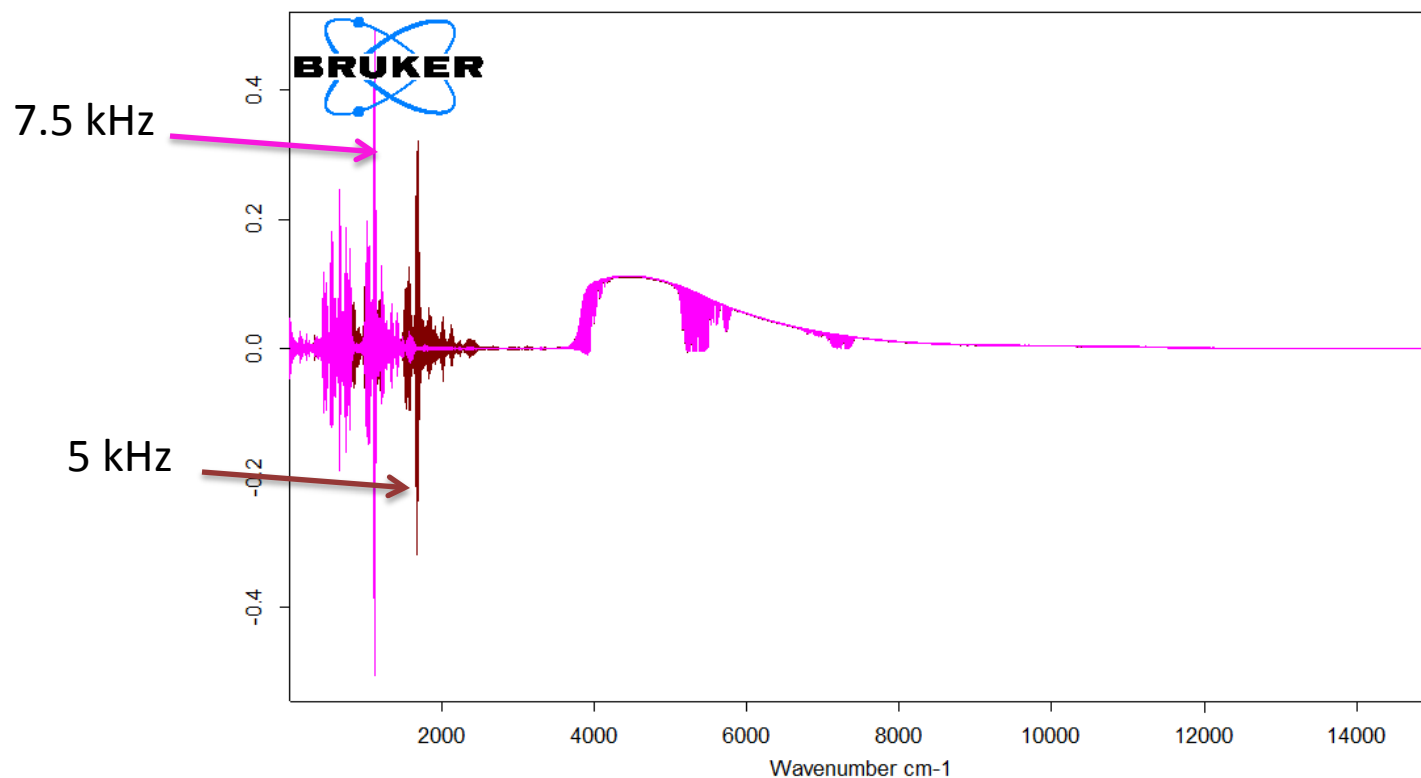


Lamp Scans



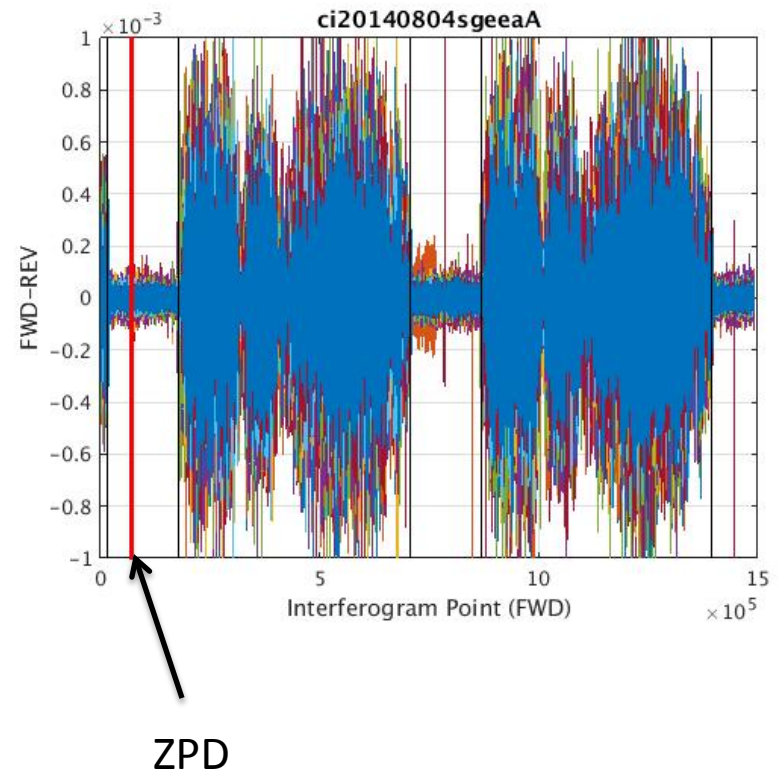
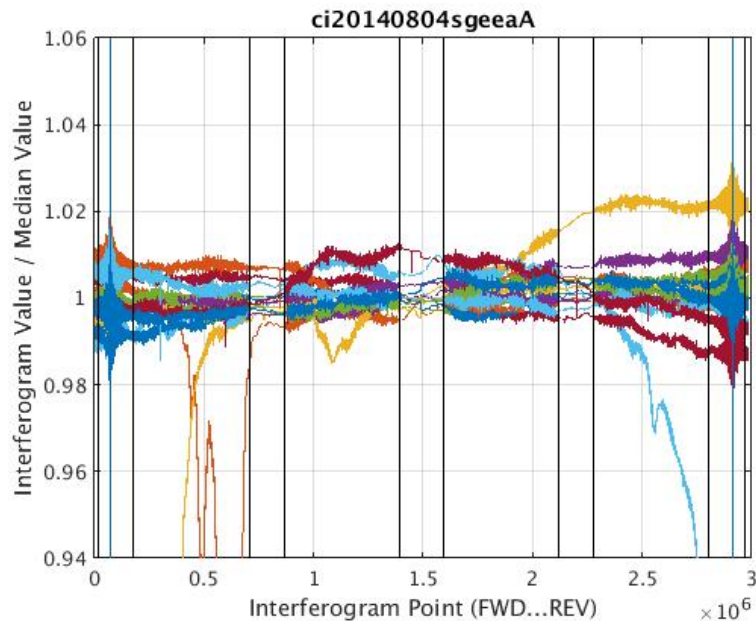
- Remarkably symmetric about MOPD
- Points to scanner motor/encoder assembly as possible culprit
- Can hear periodic “grinding/whining” noise as scanner moves: is perfectly correlated with noise bursts

Spectra Show Large Noise Pulses < 2500 cm⁻¹

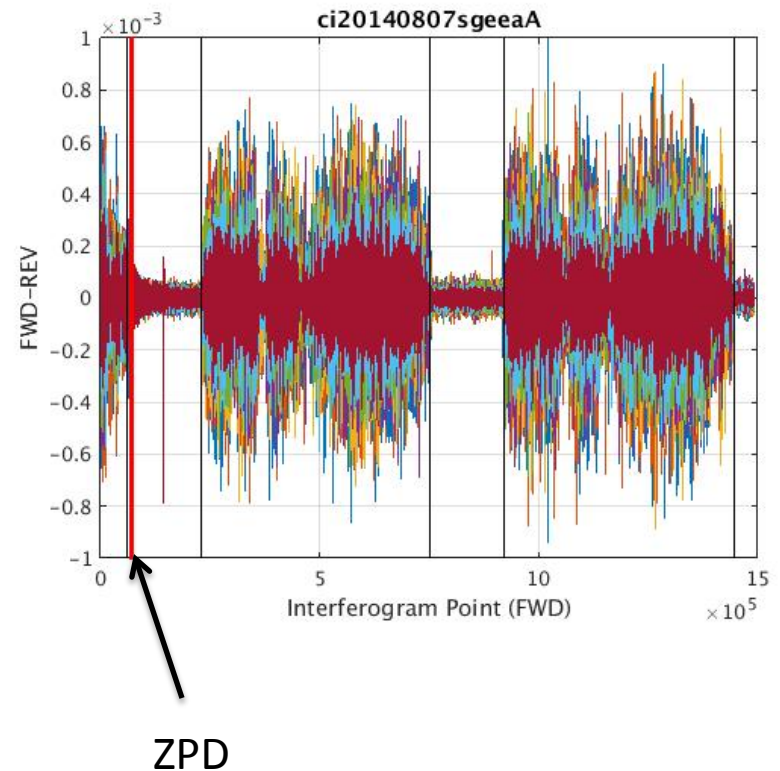
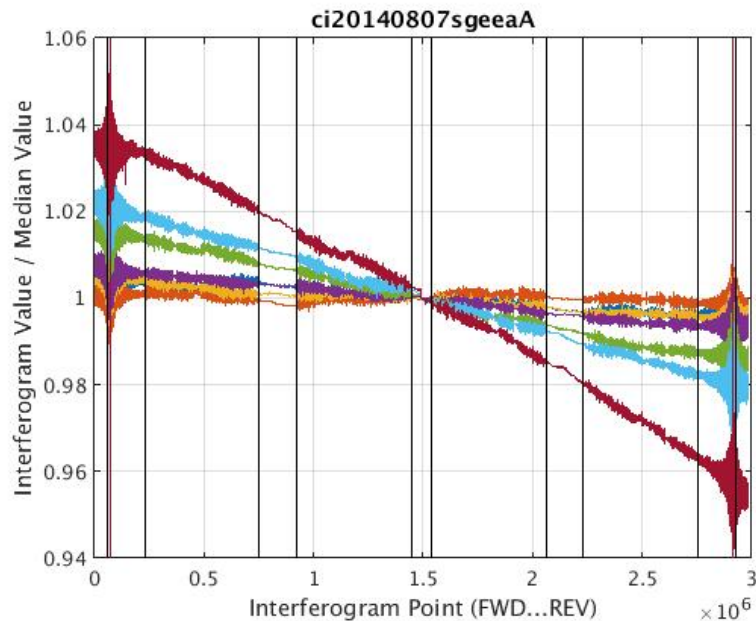


- These noise bursts wouldn't be a problem for our retrievals if they were just noise below 2500 cm⁻¹
- However, we believe that what is causing the noise bursts also mis-sampled the interferograms, which will significantly impact the retrievals!

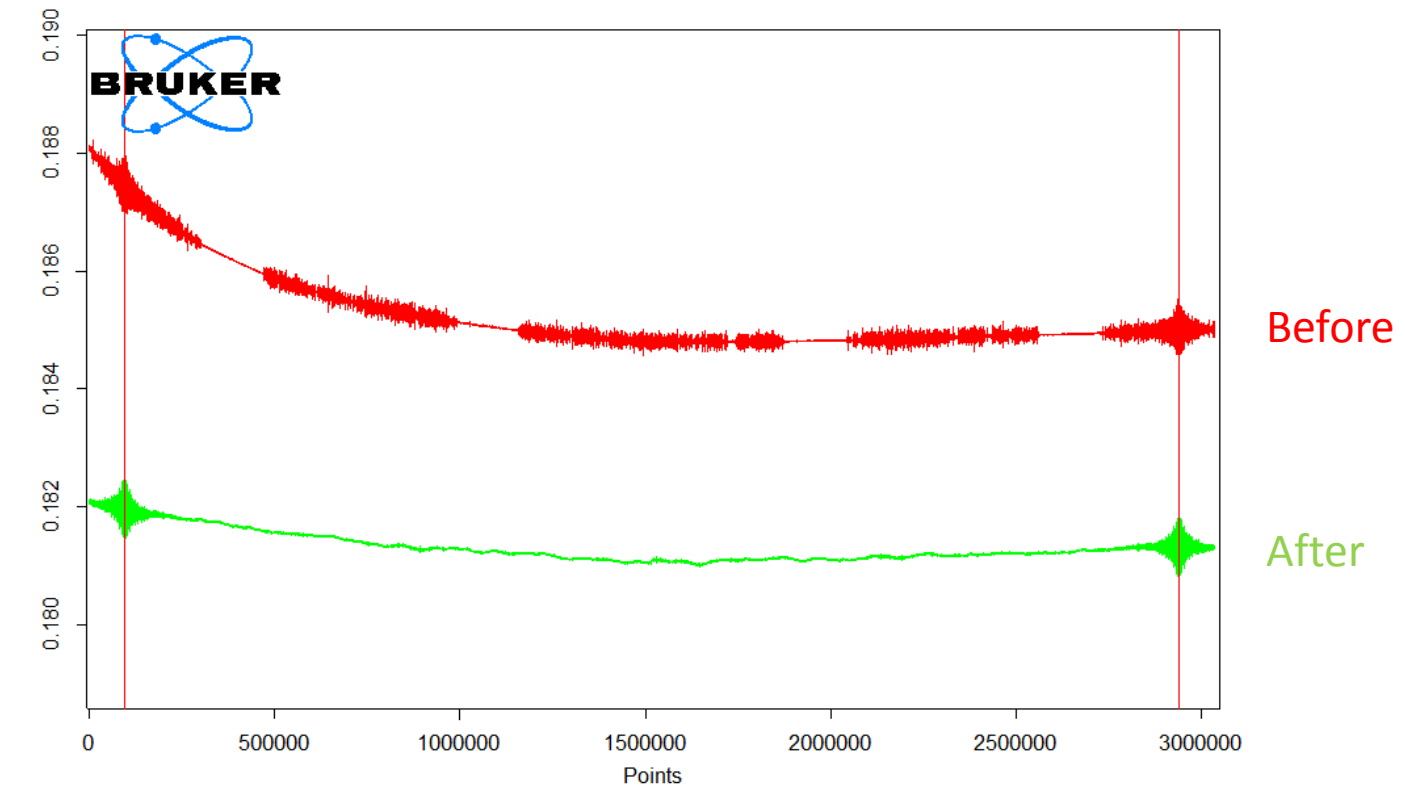
Interferograms on Day with Small FWD/REV Difference



Interferograms on Day with Large FWD/REV Difference

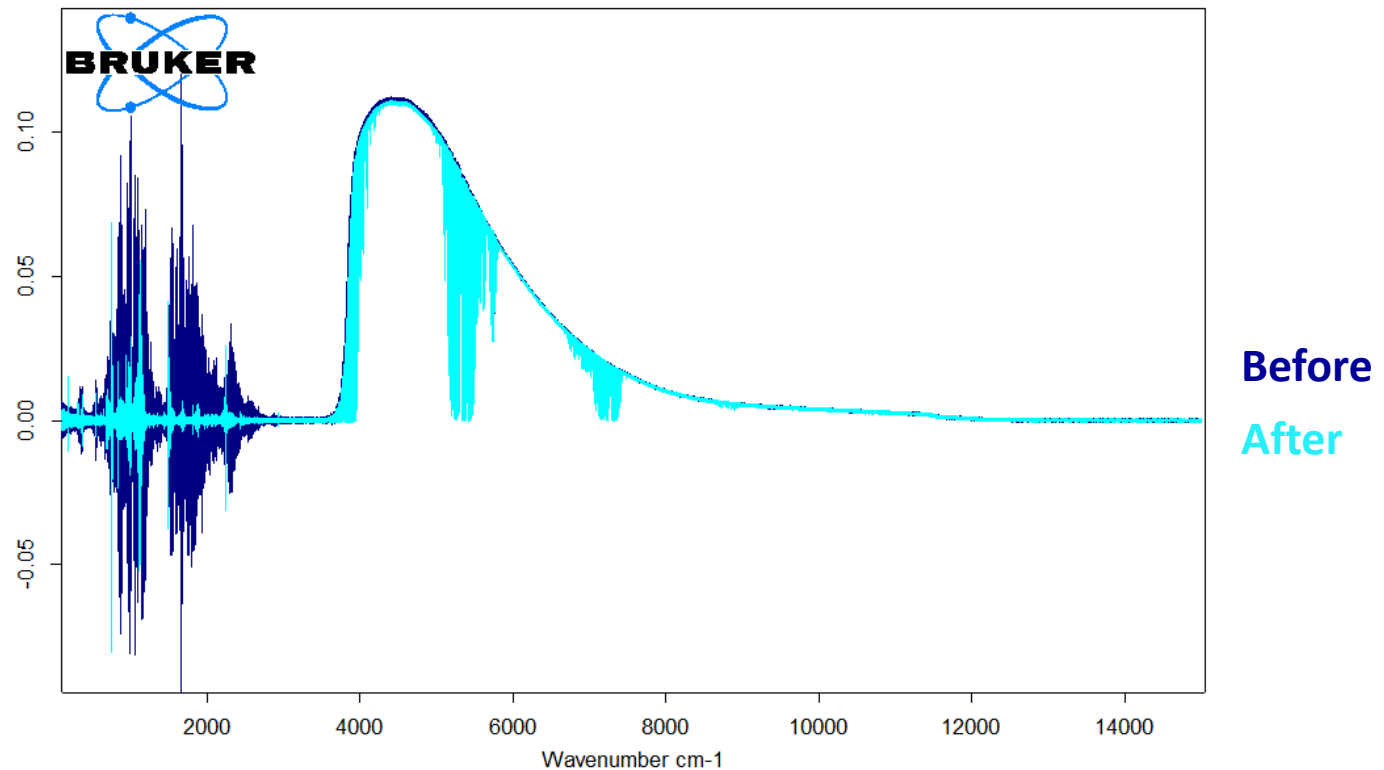


Swapping out Scanner Encoder/Motor Assembly (5 kHz)



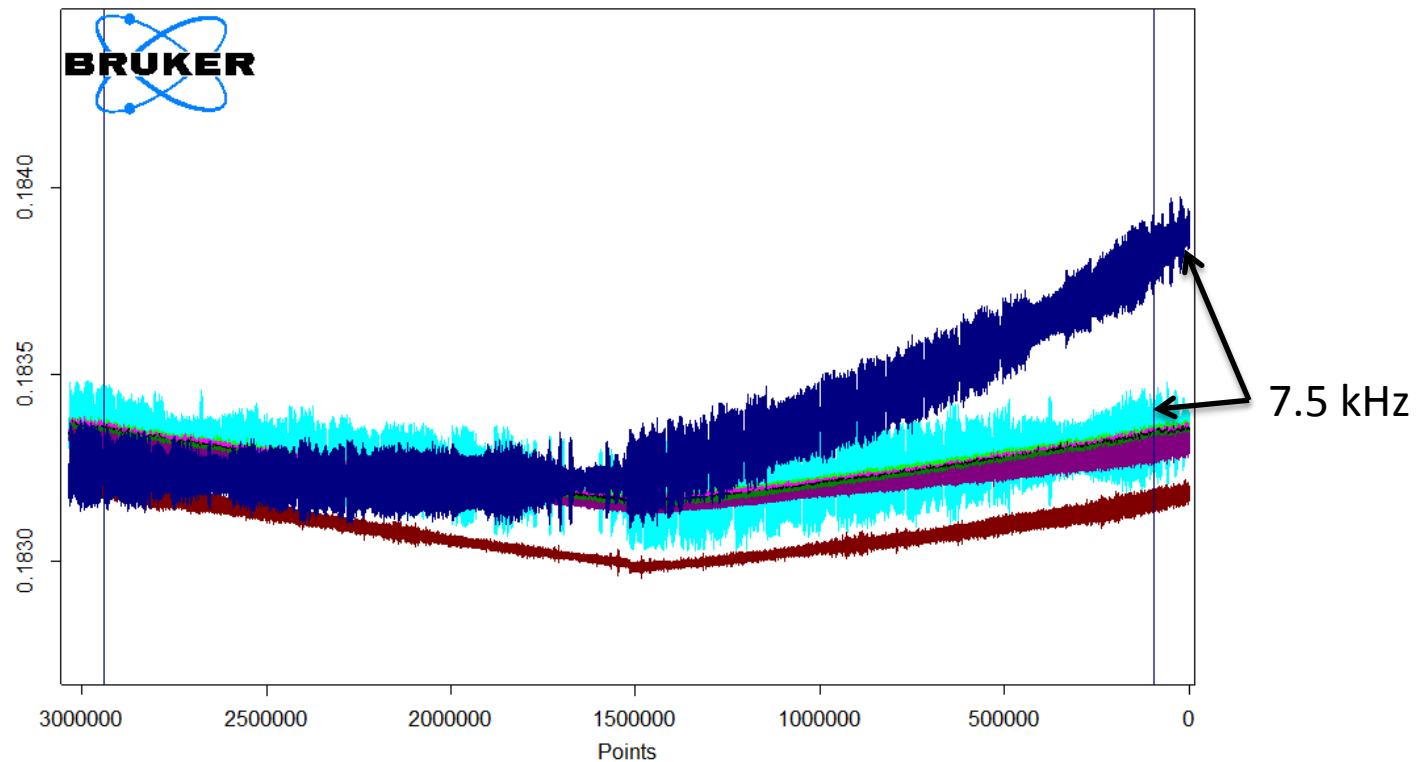
| | | | |
|--------------------------------------------|-------------|-------------|-----------|
| C:\Users\TCCON\Bruker\ci20150420\aaaaa.001 | Lab Cell #2 | Lab Cell #2 | 4/20/2015 |
| C:\Users\TCCON\Bruker\ci20150420\aaaaa.002 | Lab Cell #2 | Lab Cell #2 | 4/20/2015 |

Swapping out Scanner Encoder/Motor Assembly (5 kHz)

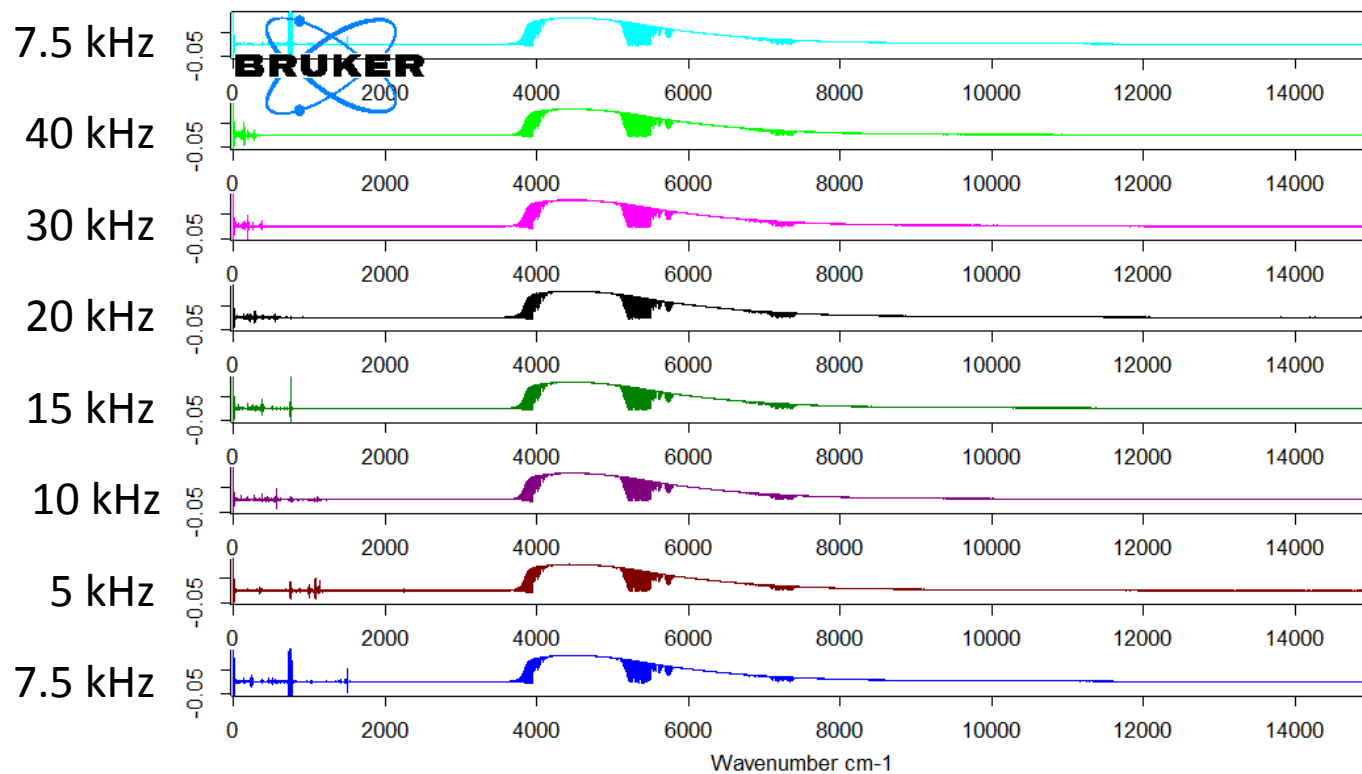


| | | | |
|--------------------------------------------|-------------|-------------|-----------|
| C:\Users\TCCON\Bruker\ci20150420\aaaaa.002 | Lab Cell #2 | Lab Cell #2 | 4/20/2015 |
| C:\Users\TCCON\Bruker\ci20150420\aaaaa.001 | Lab Cell #2 | Lab Cell #2 | 4/20/2015 |

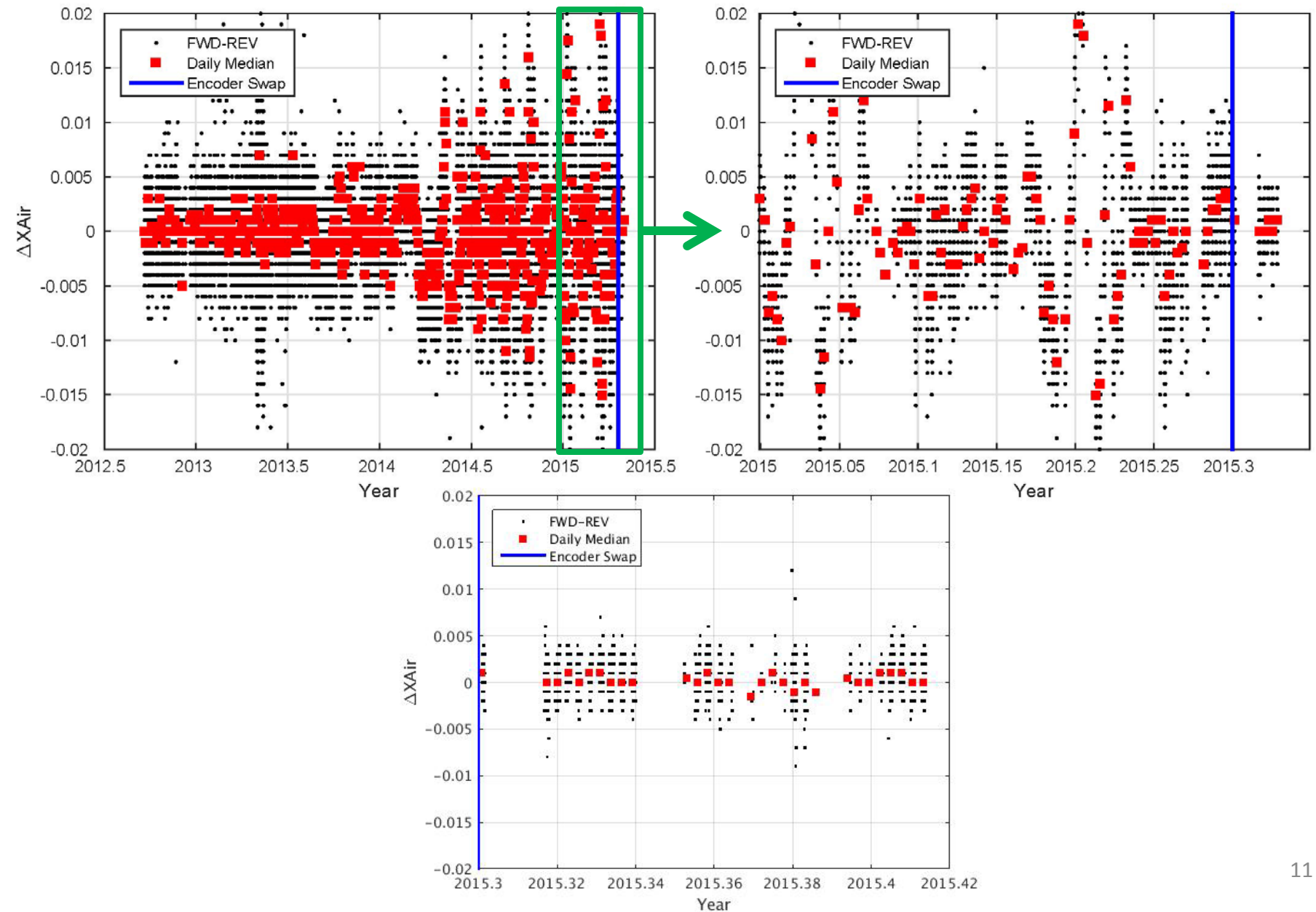
After Replacing Encoder/Motor Assembly (variety of scan speeds)



After Replacing Encoder/Motor Assembly (variety of scan speeds)

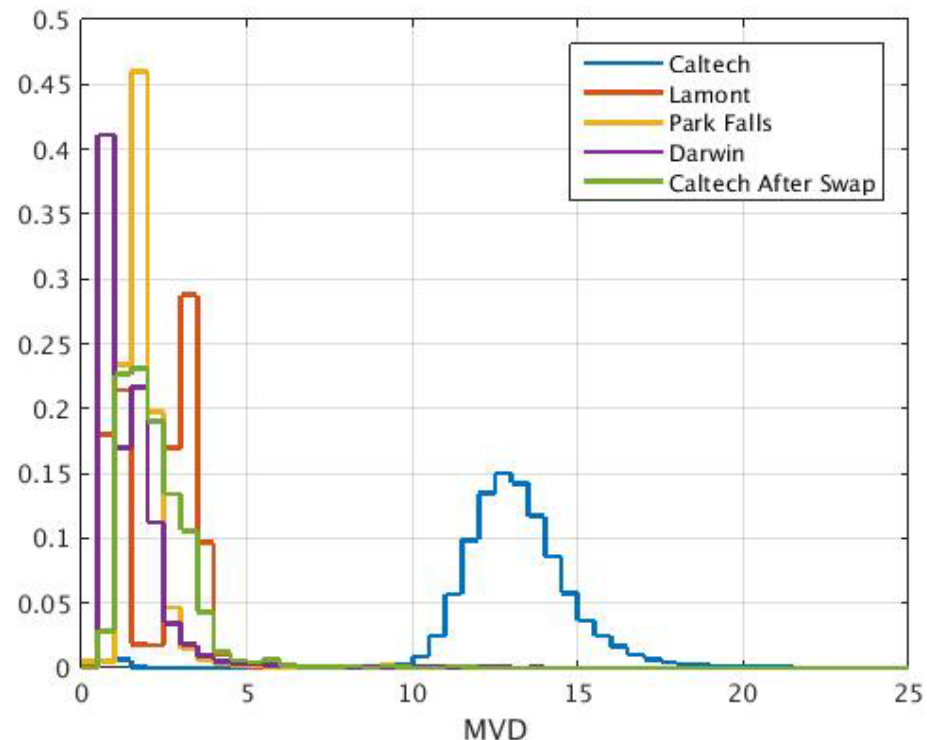


Xair differences after replacing the encoder/motor assembly

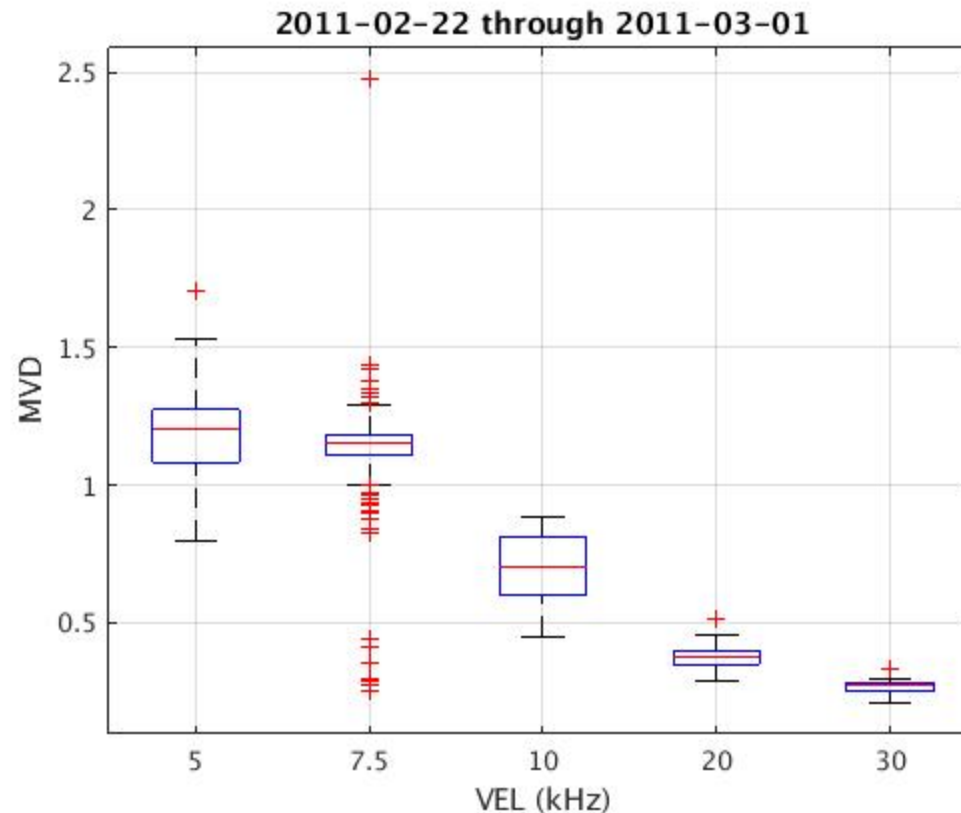


A possible diagnostic: Maximum Velocity Deviation (MVD)

- MVD is a parameter in the interferogram/slice headers, not in the GGG2014 I2S spectrum headers
 - MVD has been added for the next GGG release
- The MVD value is in percentage, and represents the maximum velocity speed deviation over all scans during acquisition.
 - One knock on the instrument will cause a big deviation even when all other scans were smooth and quiet.
 - Damage to the rods may also cause a higher MVD while the scanner passes the damaged area.
 - We should not over estimate the utility of this parameter. However, it provides a hint as to how smoothly the scanner runs.
 - For measurements with solid beam splitters like CaF_2 the MVD is usually <2 .
- Values should be small (Gregor says <2 , we see typically <5 ; Caltech was ~ 12)

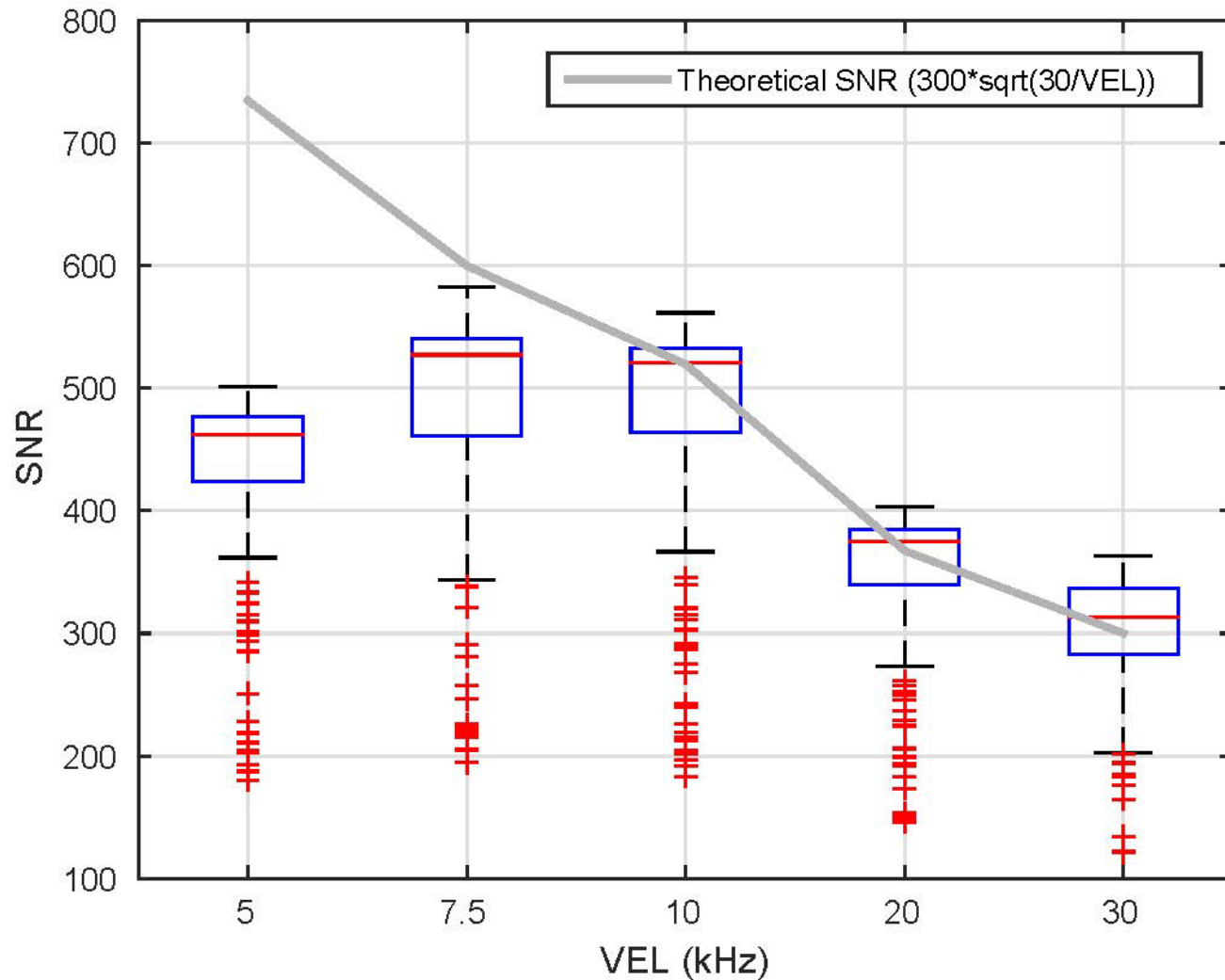


MVD as a function of Scanner Velocity (at Lamont)

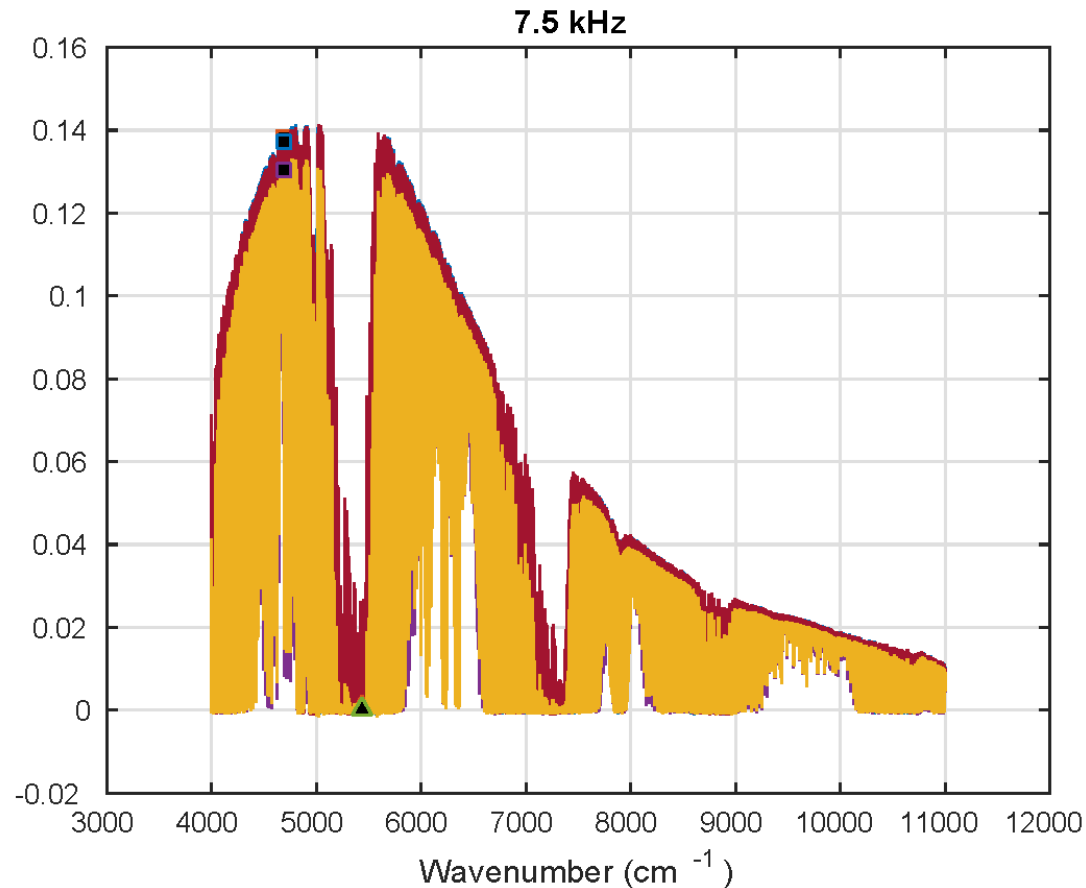


- Many more 7.5 kHz scans than the rest
- Significant difference between 7.5 kHz and 10 kHz in the motor stability
- You'd think SNR would decrease as a function of VEL, but perhaps this is partly mitigated by the MVD decrease?

SNR as a function of Scanner Velocity (at Lamont)

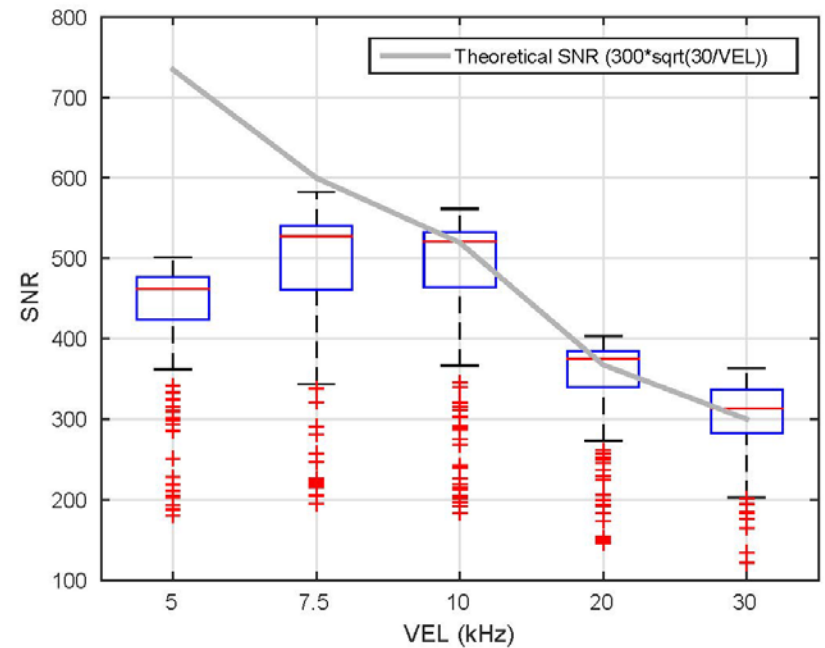
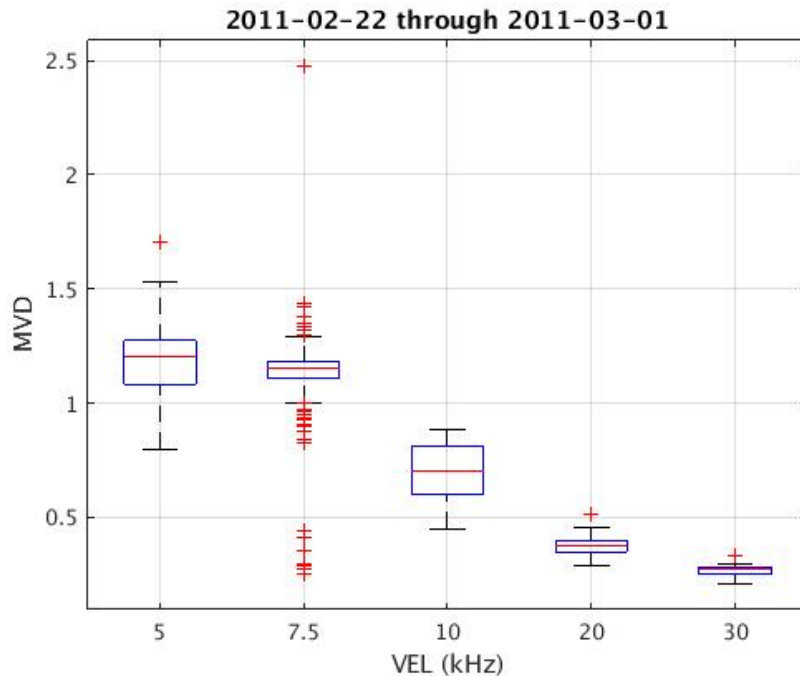


SNR Calculation/Estimation (Lamont)



- Signal taken as median value between [4683 4685]
- Noise taken as standard deviation between [5430 5450]

What Speed Should We Use? (Lamont)

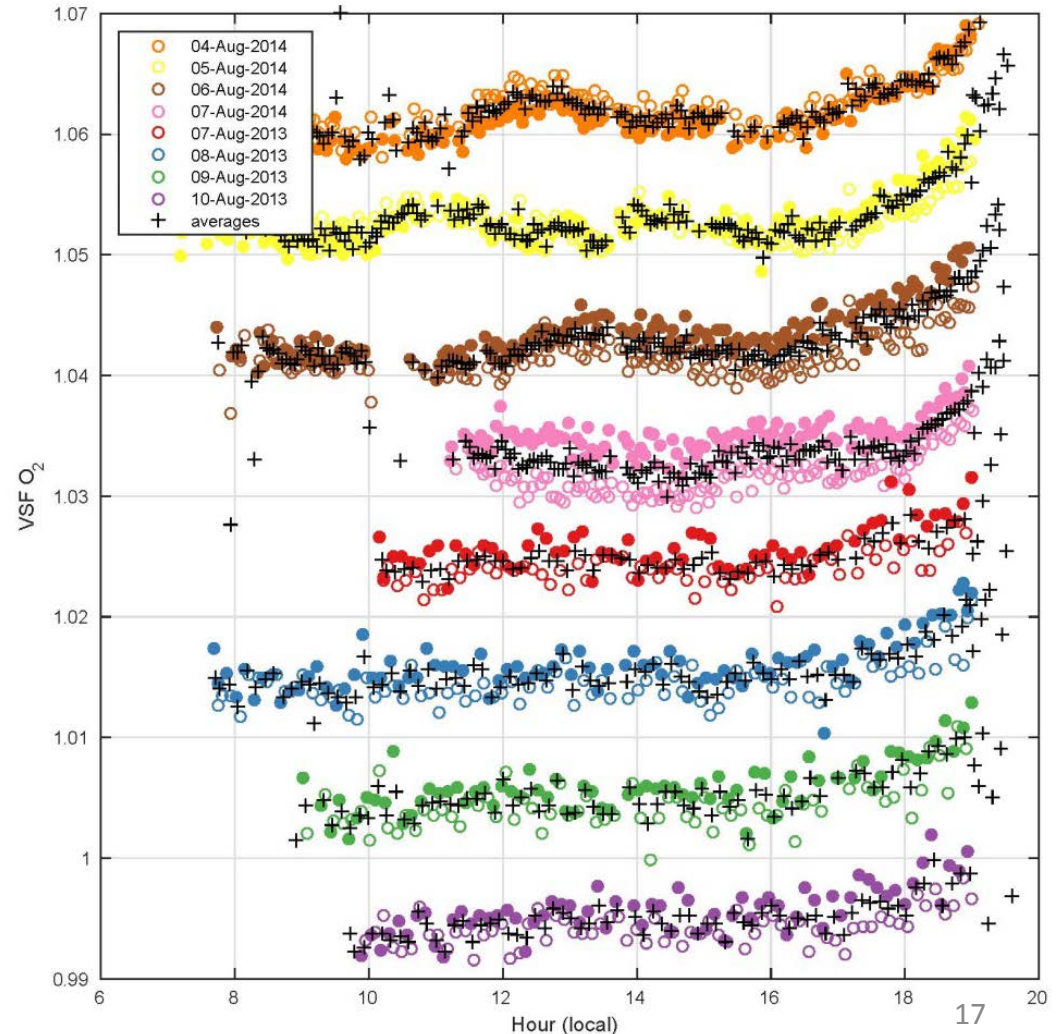


- Looks like 10 kHz is optimal: it has the highest SNR and a reasonably stable MVD

Mitigation Strategy for Historical Caltech

Data: Averaging FWD/REV Pairs

- The “+” in the plot to the right have been produced by averaging FWD/REV pairs of spectra, and then running GFIT on the averaged spectra.
- Because the results are so linear (i.e., averaging spectra gives the same result as averaging the VSF), we can average the historical forward/reverse Xgas results.



Lessons Learned and Future Work

- Shows benefit of analysing forward and reverse scans separately: we would never have known about this problem if we immediately averaged spectra!
- Run at 10 kHz.
- Monitor MVD.
- Determine component resonant at 7.5 kHz and tighten/minimize resonance.
 - Gregor Surawicz has seen this resonance signature before in other instruments, so perhaps this is not a likely outcome.